

VaR estimation and sample sizes



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VaR fluctuations – by accident or systematic?

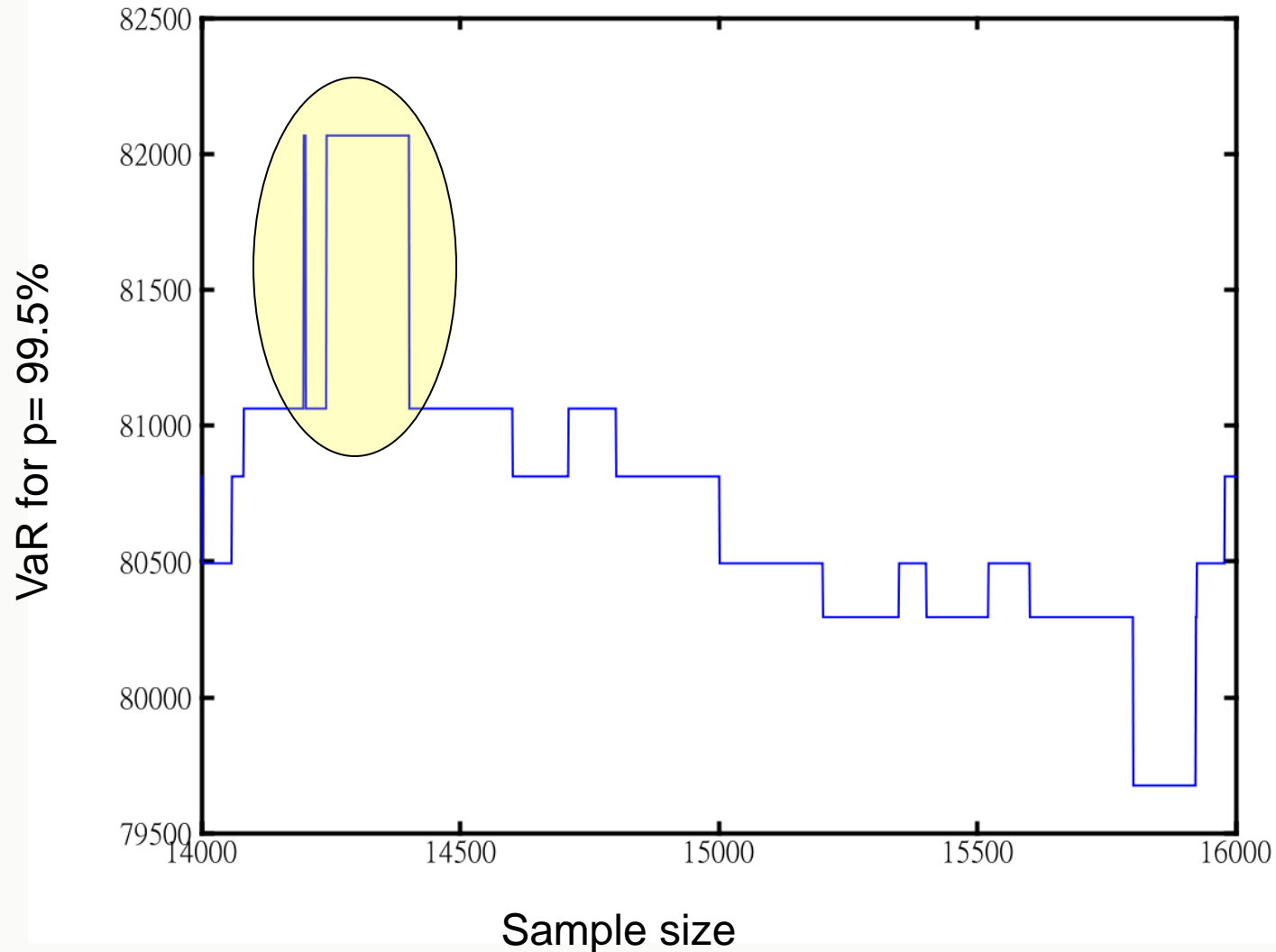
Distribution: Pareto, $\alpha = 1.2$, $\beta = 1000$

$p = 99.5\%$

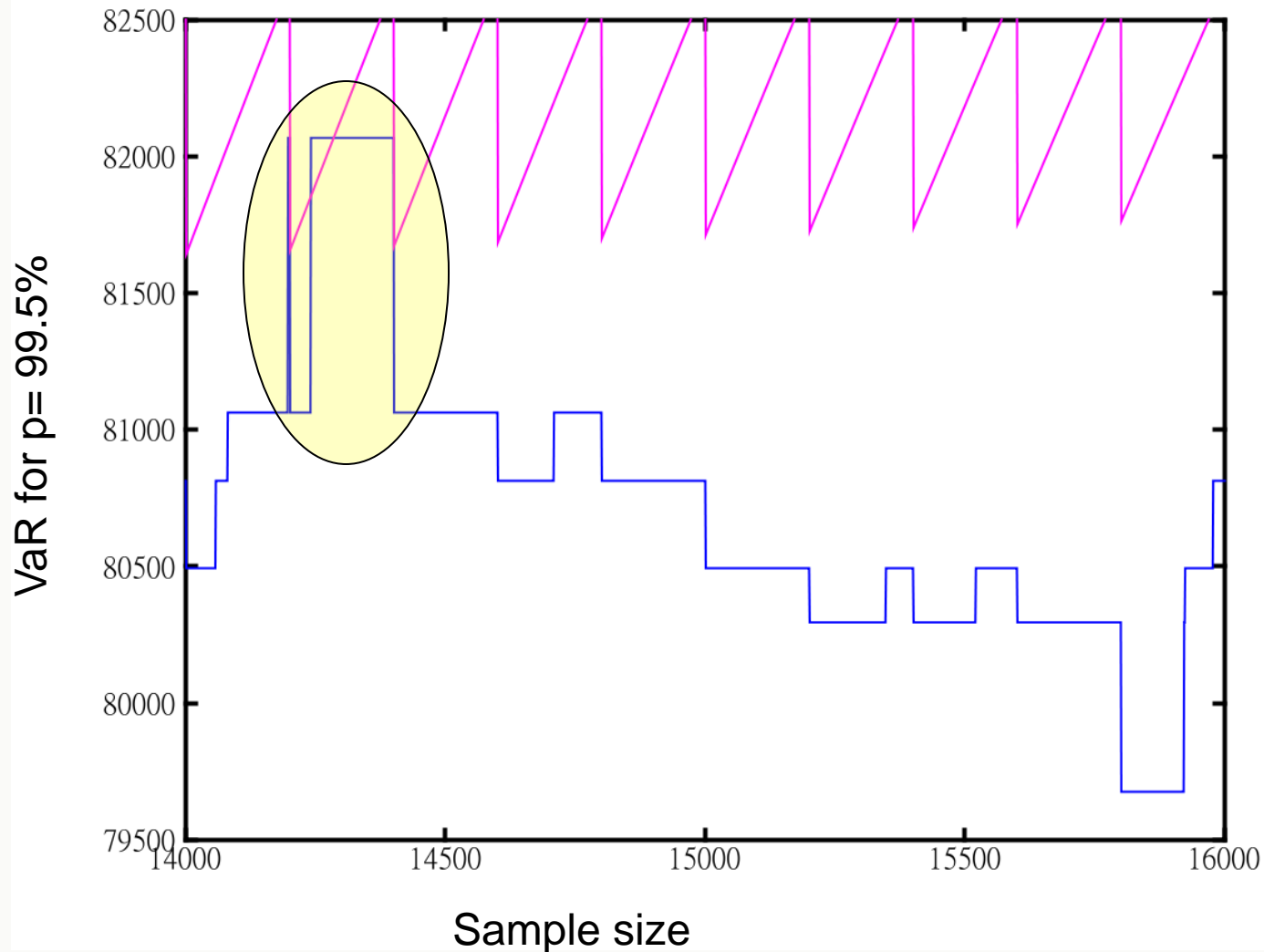
VaR derived from sample size $n = 14'250$: 82'100

VaR derived from sample size $n = 14'400$: 81'100

VaR fluctuations – by accident or systematic?

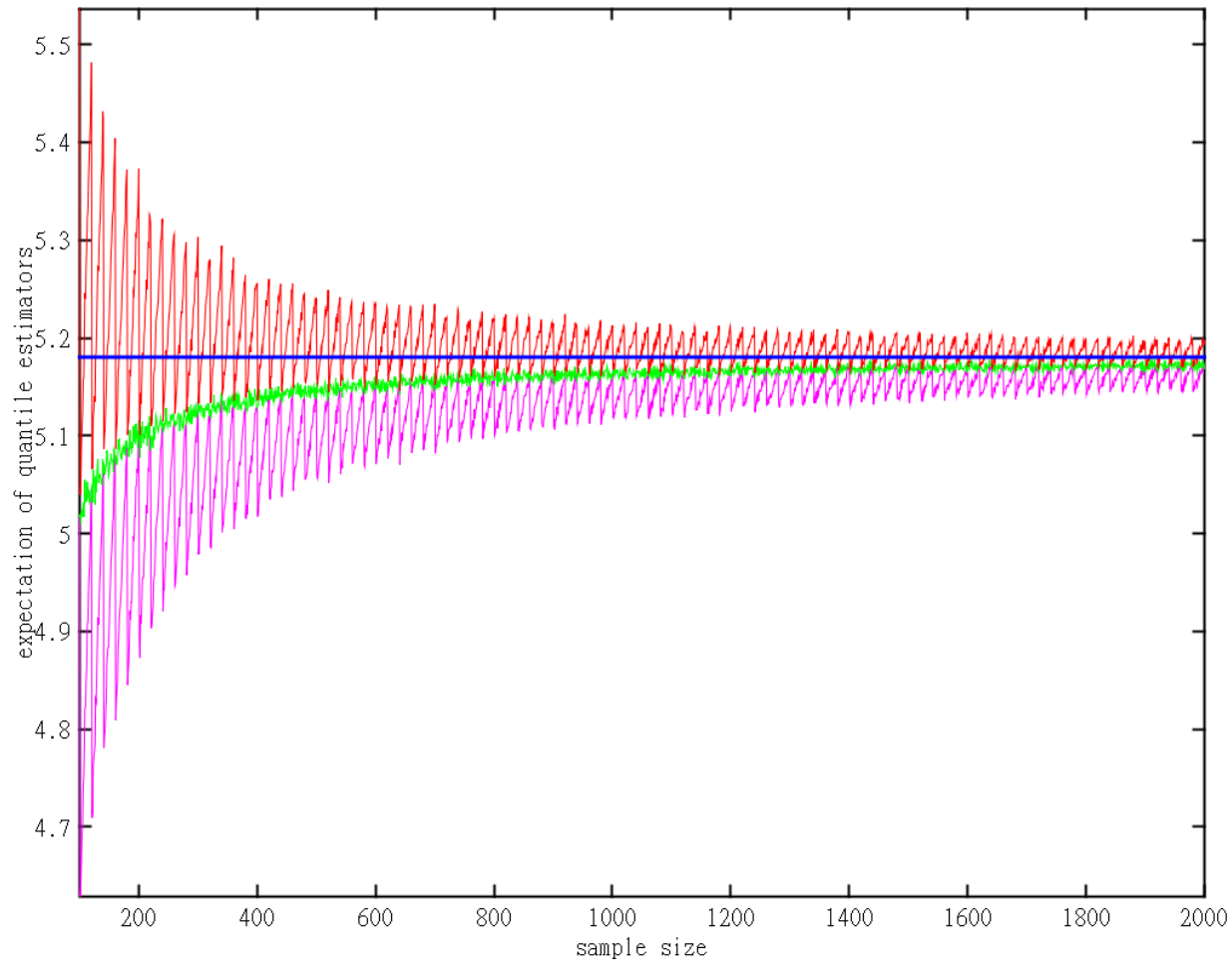


VaR fluctuations – by accident or systematic?



Saw-tooth oscillation of the bias of a simple one-point estimators

VaR for $p=95\%$, lognormal(0,1)



- Decomposition of the bias for
 - one-point estimators for uniform distributions
 - smoothed two-point estimator
- Hints to construct optimized sample estimators
- Derive heuristics for required sample sizes

Results from the paper „On VaR estimation and sample sizes“, submitted to the European Actuarial Journal.

Decomposition of the bias

Uniform distribution, one point estimator

Let x_1, x_2, \dots, x_n be a sample of size n drawn from independent, uniformly distributed random variables.

Denote with $x_{(1)}, \dots, x_{(n)}$ the sample ordered by increasing size (order statistics).

Let p be the percentile, $g := pn + o(n)$ and the one-point estimator

$$\hat{x}_p := X_{(\lfloor g \rfloor)}.$$

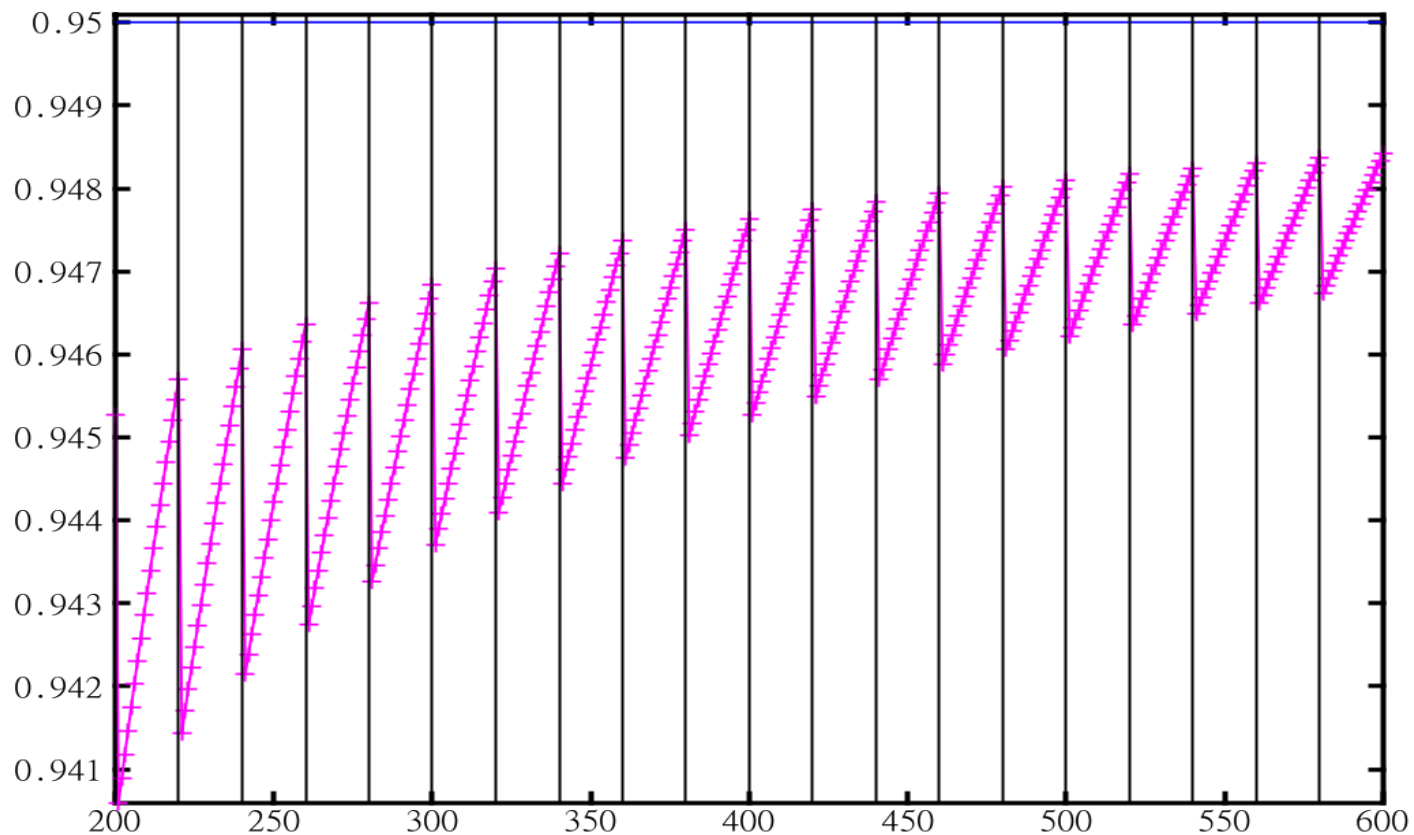
Discretization error of \hat{x}_p : $DE(\hat{x}_p) := -\frac{g - \lfloor g \rfloor}{n+1} \leq 0$

Sample error of \hat{x}_p : $SE(\hat{x}_p) := \frac{g - p(n+1)}{n+1}$

Lemma: The bias decomposition is $E[\hat{x}_p] = p + DE(\hat{x}_p) + SE(\hat{x}_p)$

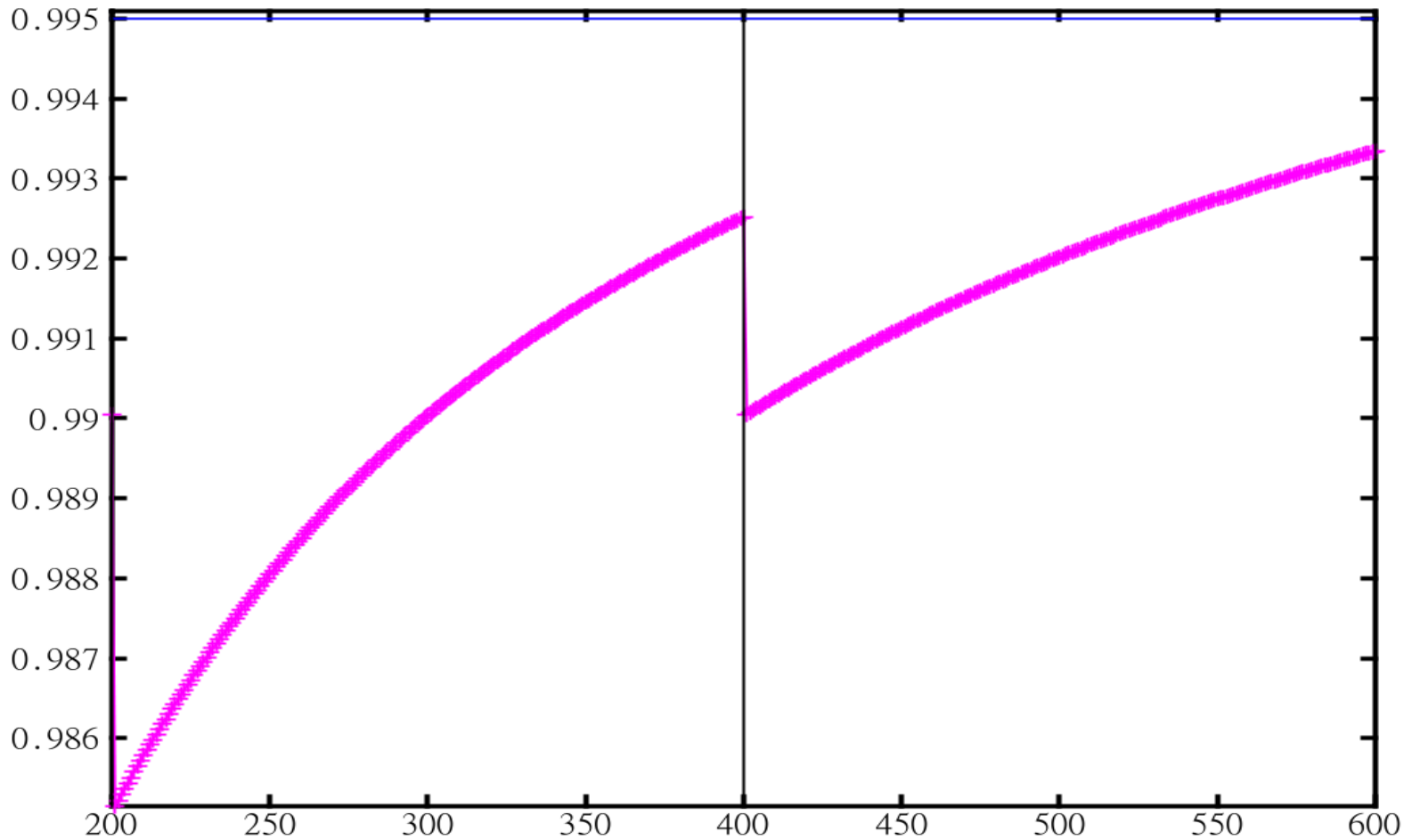
Uniform distribution, one point estimator

VaR for $p=95\%$, uniform(0,1)



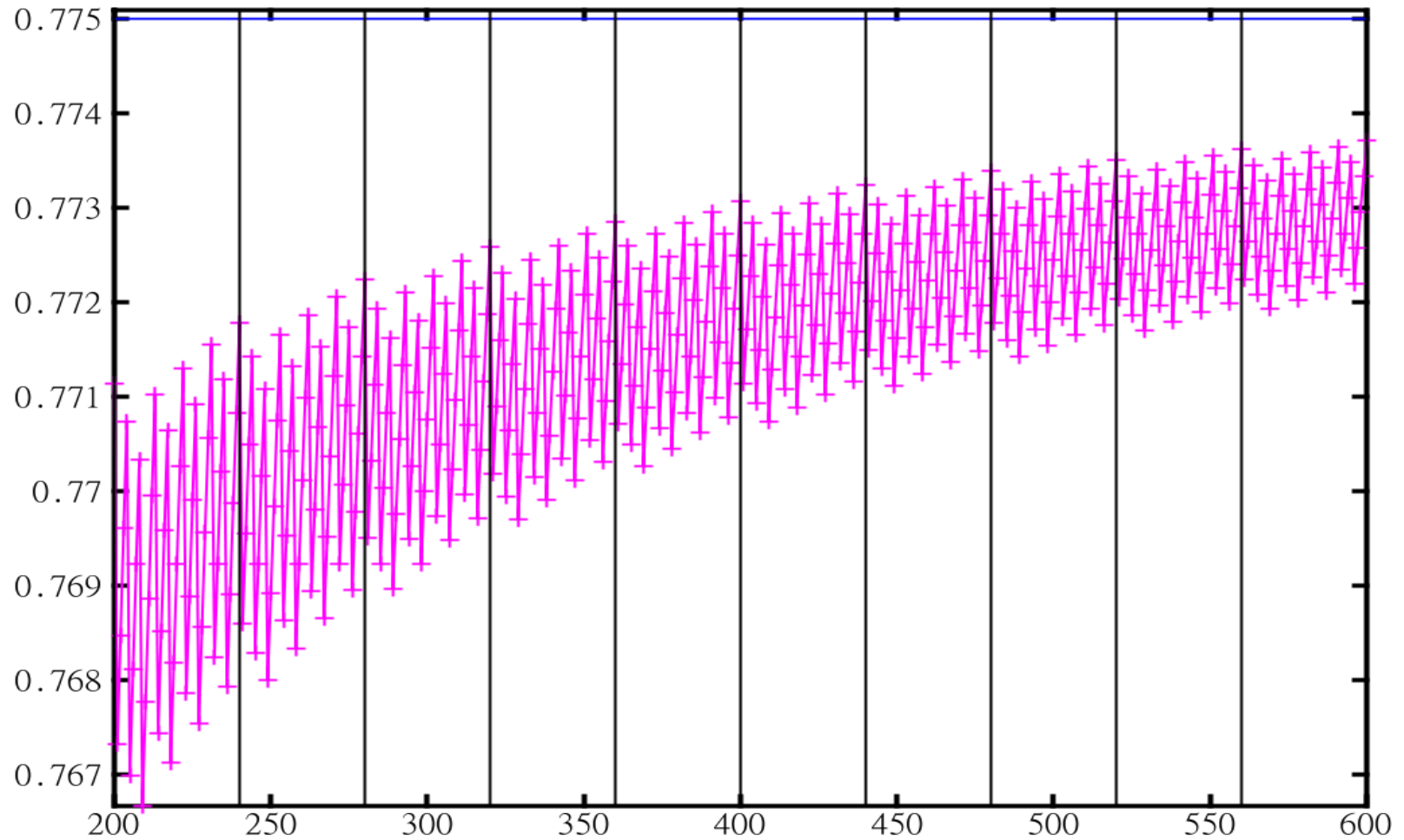
Uniform distribution, one point estimator

VaR for $p=99.5\%$, uniform(0,1)



Uniform distribution, one point estimator

VaR for $p=77.5\%$, uniform(0,1)



Decomposition of the bias

Uniform distribution, smoothed estimator

Let $g := pn + c_p$ and the weight factor $\gamma \in [0,1]$, we define the smoothed two-point estimator as

$$\hat{x}_p := \gamma \cdot X_{(\lfloor g \rfloor)} + (1 - \gamma) \cdot X_{(\lceil g \rceil)}$$

Lemma: For suitably generalized definitions of discretization error and sample error the bias decomposition is

$$E[\hat{x}_p] = p + DE(\hat{x}_p) + SE(\hat{x}_p)$$

with

$$SE(\hat{x}_p) = \frac{g - p(n+1)}{n+1} = \frac{c_p - p}{n+1}$$

$$DE(\hat{x}_p) = -\frac{g - \lfloor g \rfloor}{n+1} + \frac{\gamma}{n+1} (1 - \delta(g - \lfloor g \rfloor))$$

$$DE(\hat{x}_p) = 0 \text{ if and only if } n \in N \text{ such that } \gamma = g - \lfloor g \rfloor$$

Decomposition of the bias

General distribution, smoothed estimator

Proposition: The bias decomposition is

$$E[\hat{x}_p] = x_p + \frac{DE(\hat{x}_p) + SE(\hat{x}_p)}{f(x_p)} - \frac{p(1-p)}{2(n+2)} R + O(n^{-2})$$

with R of order one and a function of f' and f^{-3}

For the uniform distribution this decomposition is the earlier lemma.

The position g which yields the unbiased estimator for the uniform distribution is not necessarily a good choice for general distributions. Good choices are dependent of f and exploit the fact that the error terms have different signs.

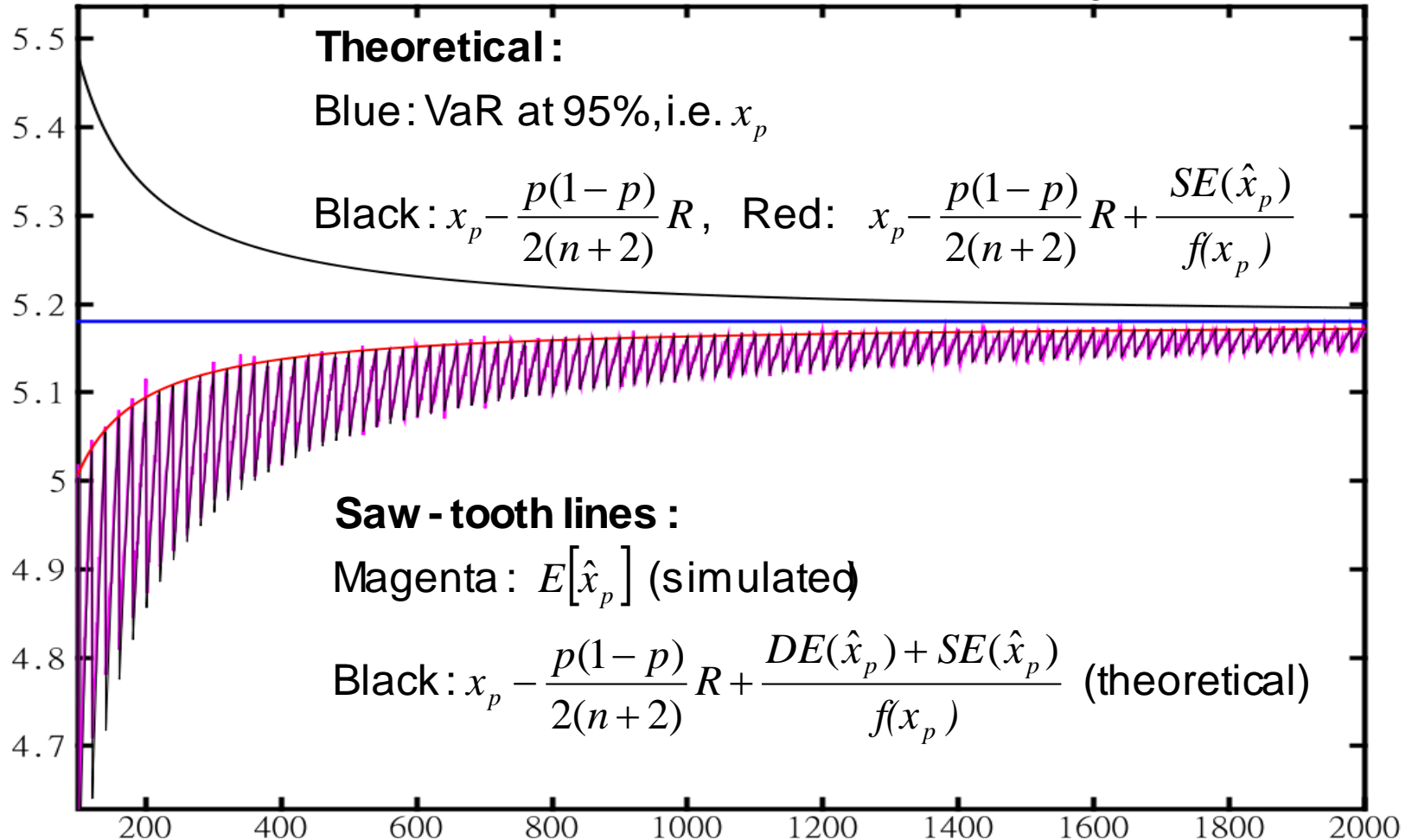
One can also optimize the median of the error instead of its expectation.

Hyndman and Fan's chose the g in such a way:

$$\hat{x}_p := (1-\gamma)x_{(\lfloor g \rfloor)} + \gamma x_{(\lceil g \rceil)} \quad \text{with} \quad g = p(n + \frac{1}{3}) + \frac{1}{3} \quad \text{and} \quad \gamma = g - \lfloor g \rfloor$$

General distribution – Verification of results

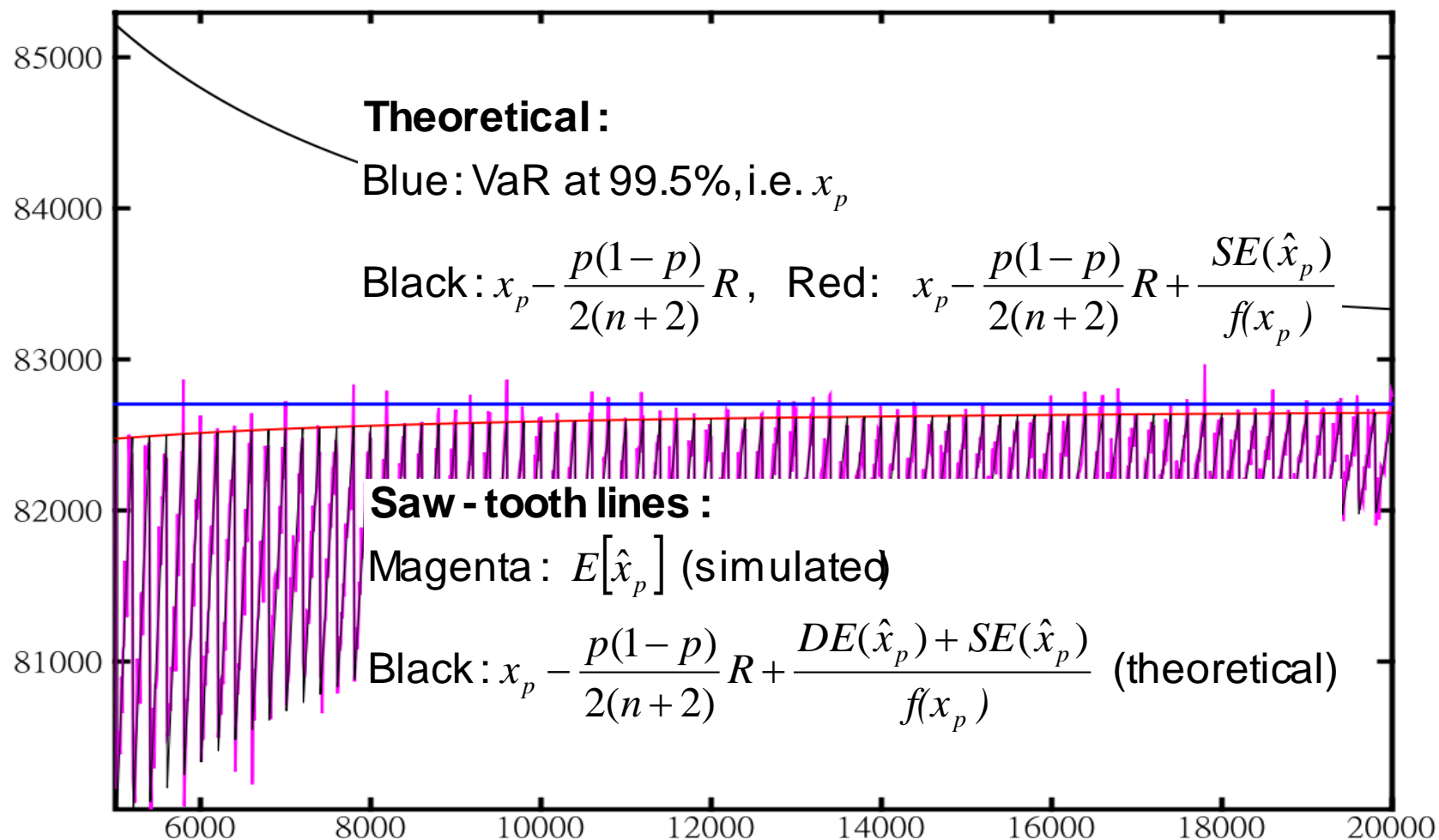
Bias decomposition for low side estimator: VaR 95%, lognormal(0,1)



Simulated results are visually almost indistinguishable from the theoretical results

Examples

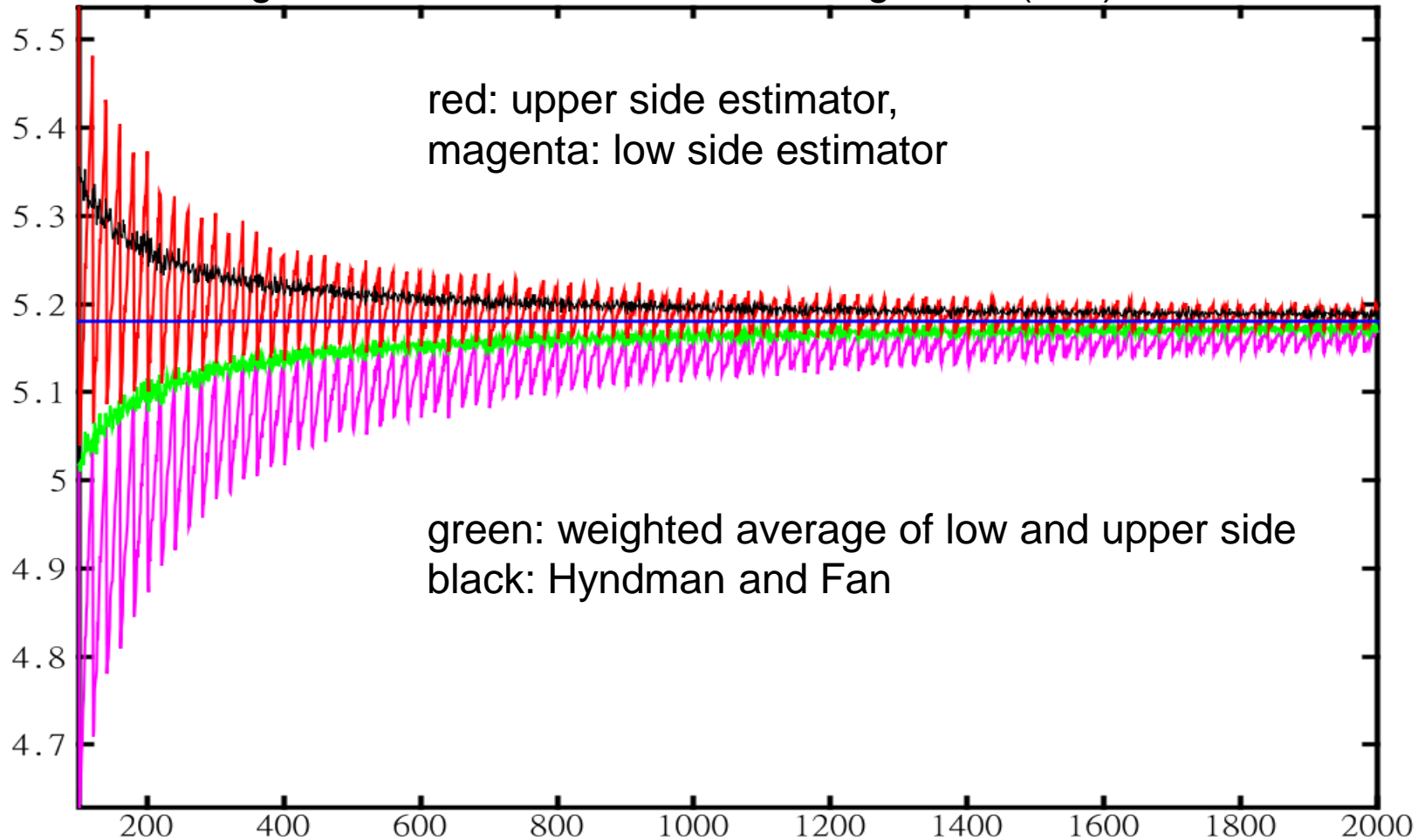
Bias decomposition for low side estimator: VaR 99.5%, Pareto(1.2, 1000)



Simulated results are visually almost indistinguishable from the theoretical results

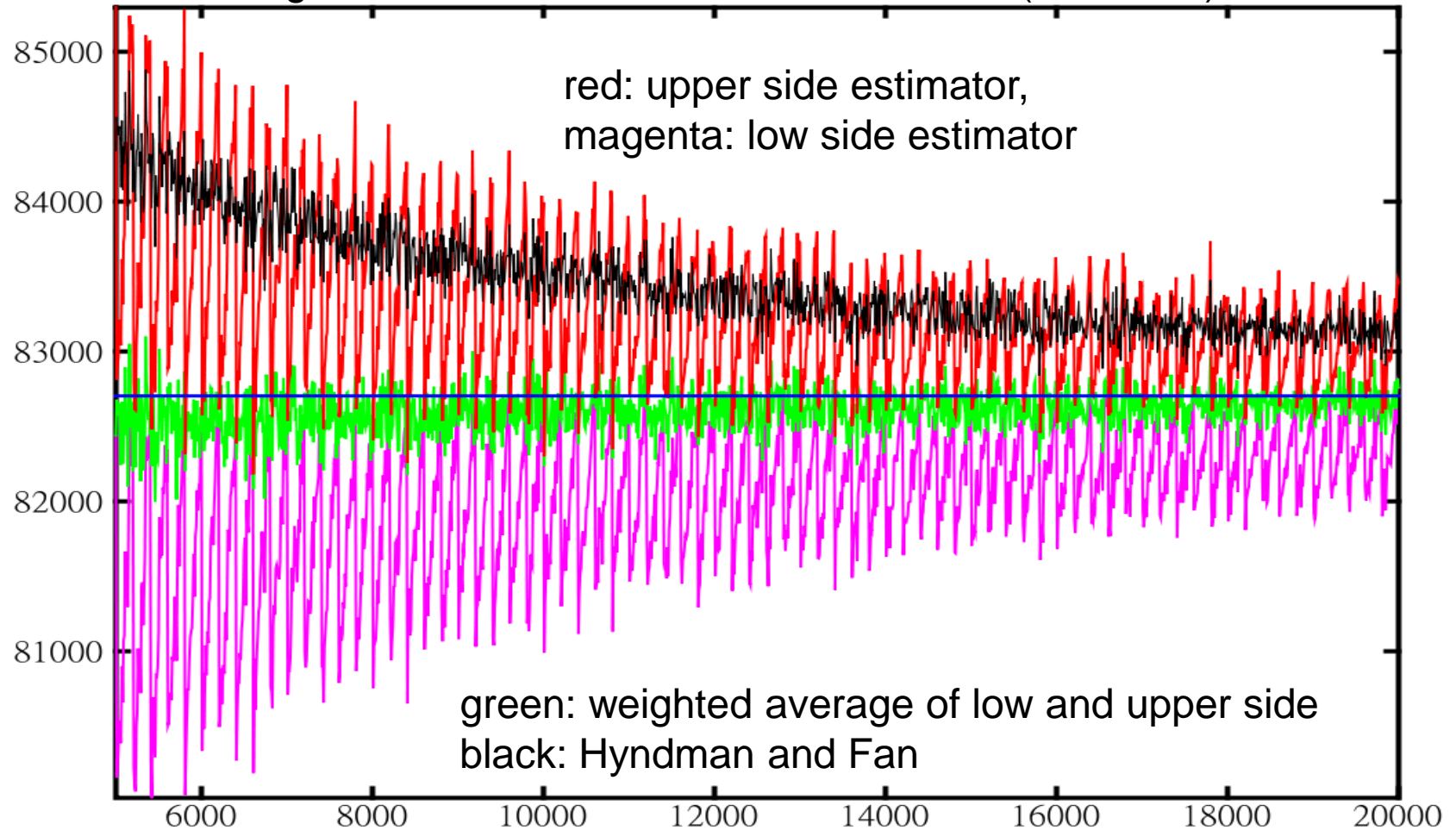
The best smoothing depends on tail behavior and p

Smoothing of VaR estimators: VaR 95%, lognormal(0, 1)



The best smoothing depends on tail behavior and p

Smoothing of VaR estimators: VaR 99.5%, Pareto(1.2, 1000)



For heavy tail distributions, the Hyndman and Fan is not the best estimator.

Conclusions

- If at all, one-point estimators should only be used for very specific order statistics
- A good smoothing depends on the tail behavior of the distribution
- A good smoothing depends on the VaR level